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## **2050 MTP PROJECT FACT SHEET**

Short Title	PATH 400 TRAIL FROM WIEUCA ROAD TO LORIDANS DRIVE	Mentagada Articologia de La Control de La Co
GDOT Project No.	0015997	Mountain Way
Federal ID No.	N/A	Danube Rd NE
Status	Programmed	Wieuca Tree No.
Service Type	Last Mile Connectivity / Sidepaths and Trails	Mienca Lice N N 19 Page 18 18 18 18 18 18 18 18 18 18 18 18 18
Sponsor	City of Atlanta,Livable Buckhead	Wieuca A NO
Jurisdiction	City of Atlanta	NE S 0 250 500 Feet
Analysis Level	Exempt from Air Quality Analysis (40 CFR 93)	3
Existing Thru Lane	N/A LCI	Network Year TBD
Planned Thru Lane	N/A Flex	Corridor Length N/A miles
Detailed Description a	nd Justification	
employment centers. PATH4 the Atlanta Beltline. PATH40	ss to develop a connected regional trail network - including 400 provides a critical link in the region's trail network, ope 0 provides critical intermodal connectivity with direct acces etwork is a high regional priority to provide alternative trar	ning the entire north metro area to access the system and s to Lindbergh, Lenox and Buckhead MARTA stations. The

Phase Status & Funding Status		FISCAL	TOTAL PHASE	BREAKDOWN OF TOTAL PHASE COST BY FUNDING SOURCE				
Information			YEAR	COST	FEDERAL	STATE	BONDS	LOCAL/PRIVATE
PE	Surface Transportation Block Grant (STBG) Program - Urban (>200K) (ARC)	AUTH	2019	\$790,000	<del>\$632,000</del>	<del>\$0,000</del>	<del>\$0,000</del>	<del>\$158,000</del>
CST	Transportation Alternatives (Section 133(h)) - Urban (>200K) (ARC)	AUTH	2022	\$10,944,608	<del>\$8,755,686</del>	<del>\$0,000</del>	<del>\$0,000</del>	<del>\$2,188,922</del>
CST	Surface Transportation Block Grant (STBG) Program - Urban (>200K) (ARC)		2024	\$1,000,000	\$800,000	\$0,000	\$0,000	\$200,000
				\$12,734,608	\$10,187,686	\$0,000	\$0,000	\$2,546,922

SCP: Scoping PE: Preliminary engineering / engineering / design / planning PE-OV: GDOT oversight services for engineering ROW: Right-of-way Acquistion UTL: Utility relocation CST: Construction / Implementation ALL: Total estimated cost, inclusive of all phases

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